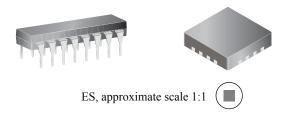


# 3 Bit Constant Current LED Driver with PWM Control

#### **Features and Benefits**

- 5 to 17 V operation
- Wide output current range (10 to 150 mA per output)
- 3×7 bit Dot Correction current settings
- 31 bit shift register
- 3×10 bit PWM luminance settings
- Buffered output control pins
- Up to 5 MHz serial / PWM clock frequency
- Thermal Shutdown / UVLO

# Packages: 16 pin DIP (suffix A), and 16 pin QFN/MLP (suffix ES)



# **Description**

The A6280 is a 3 bit constant current LED driver that has a wide range of output currents. The A6280 controls LED luminance with a pulse width modulation (PWM) scheme that gives the application the capability of displaying a billion colors. The overall maximum current is set by an external resistor.

The LED luminance is controlled by performing PWM control on the outputs. The luminance data of the PWM signal for each LED is stored in three 10 bit registers. Each LED can be dot corrected by a 7 bit scalar register that scales the maximum current from 100% down to 36.5%. All the internal latched registers are loaded by a 31 bit serial shift register. One bit is used to control the type of data loaded into the registers, either dot correction/clock divider ratio or luminance data. The remaining 30 bits are used for the data. This helps reduce the pin count of the A6280. To further lower the A6280 pin count, the PWM clock and the serial bus clock share the same pin and work concurrently to control LED luminance and to load data.

The A6280 is designed to minimize the number of components needed to drive LEDs with large pixel spacing. Several A6280s can be daisy chained together and controlled by just four control signals (Clock, Serial Data, Latch, and Output Enable). Each of these inputs has buffered outputs on chip. Also, the VIN pin

Continued on the next page...

# **Application Diagram**

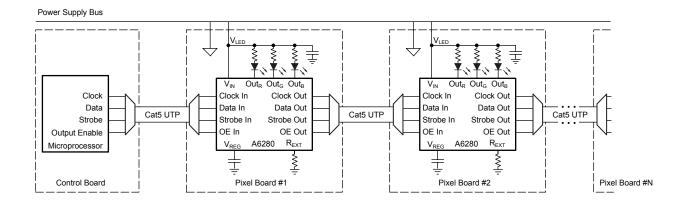


Figure 1. Functional drawing of daisy chained display application. Additional pixel boards with A6280 ICs can be applied.

# A6280

# 3 Bit Constant Current LED Driver with PWM Control

# **Description (continued)**

can be tied to the LED voltage supply bus, thus eliminating the need for a separate chip supply bus or an external linear regulator.

The A6280 is supplied in a 16 pin dual in line (DIP) package (suffix 'A') package and in a 16 lead QFN/MLP (suffix 'ES') package. The packages are lead (Pb) free with 100% matte-tin leadframe plating.

#### **Selection Guide**

Part Number	Packing*	Mounting
A6280EA-T	25 pieces/tube	16 pin DIP
A6280EESTR-T	1500 pieces/reel	16 pin QFN/MLP

<sup>\*</sup>Contact Allegro for additional packing options.

#### **Absolute Maximum Ratings**

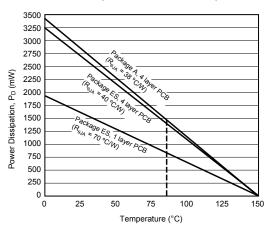
•				
Characteristic	Symbol	Notes	Rating	Units
Supply Voltage	V <sub>IN</sub>		17	V
Output Voltage	Vo		-0.5 to 17	V
Output Current	Io		170	mA
Ground Current	I <sub>GND</sub>		600	mA
Logic Input Voltage Range	V <sub>I</sub>		-0.3 to 7	V
Operating Ambient Temperature	T <sub>A</sub>	Range E	-40 to 85	°C
Maximum Junction Temperature	T <sub>J</sub> (max)		150	°C
Storage Temperature	T <sub>stg</sub>		-40 to 150	°C

#### **Thermal Characteristics**

Characteristic	Symbol	Test Conditions*	Rating	Units
		Package A, 4 layer PCB	38	°C/W
Package Thermal Resistance	$R_{ heta JA}$	Package ES, 4 layer PCB	40	°C/W
		Package ES, 1 layer PCB with 1 in <sup>2</sup> . Cu area	70	°C/W

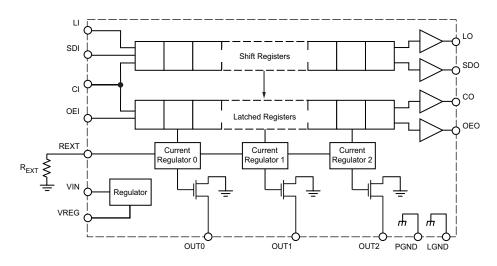
<sup>\*</sup>For additional information, refer to the Allegro website.

#### **Power Dissipation versus Ambient Temperature**

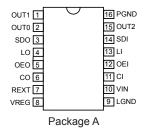


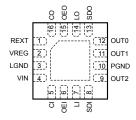


# **Functional Block Diagram**



# **Pin-out Drawings**





Package ES

#### **Terminal List Table**

Name	Nu	mber	Description						
Name	A Package	ES Package	Description						
OUT1	1	11	Sinking output terminal						
OUT0	2	12	Sinking output terminal						
SDO	3	13	Buffered serial data output after shift registers						
LO	4	14	Buffered latch output						
OEO	5	15	Buffered output enable output						
CO	CO 6 16		Buffered clock output						
REXT	7	1	An external resistor at this terminal establishes overall output current						
VREG	8	2	Regulator decoupling						
LGND	9	3	Logic ground						
VIN	10	4	Chip power supply voltage						
CI	11	5	Serial and PWM clock input						
OEI	12	6	Output enable input; when low (active), the output drivers are enabled;						
OEI	12	O	when high (inactive), all output drivers are turned off (blanked)						
LI	13	7	Latch input terminal; serial data is latched with high-level input						
SDI	14	8	Serial data input to shift registers						
OUT2	15	9	Sinking output terminal						
PGND	16	10	Power ground						



# A6280

# 3 Bit Constant Current LED Driver with PWM Control

# **OPERATING CHARACTERISTICS.** valid at $T_{\Delta} = 25^{\circ}$ C. $V_{IN} = 4.75$ to 17.0 V, unless otherwise noted

Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units	
ELECTRICAL CHARACTERISTICS							
Quiescent Supply Current	I <sub>DD</sub>	$f_{CLKIN} = 0.0 \text{ Hz}$	_	_	5.0	mA	
Operating Supply Current	I <sub>DD</sub>	f <sub>CLKIN</sub> = 5 Mhz	-	-	15.0	mA	
I landom soldono I colsos d		V <sub>IN</sub> rising	3.5	-	4.5	V	
Undervoltage Lockout	V <sub>IN(UV)</sub>	V <sub>IN</sub> falling	3.0	-	4.0	V	
VREG Voltage Range	$V_{REG}$	I <sub>O</sub> =15 mA, V <sub>IN</sub> = 17 V	4.6	-	5.4	V	
VREG Dropout Voltage	$V_{DO}$	I <sub>O</sub> =15 mA, V <sub>IN</sub> = 4.75 V	-	200	600	mV	
Outrout Comment (and also also autrout)		$R_{EXT}$ = 5 kΩ, scalar = 100%	135	150.0	165	mA	
Output Current (any single output)	Io	$R_{EXT} = 15 \text{ k}\Omega$	44	_	54	mA	
Output to Output Matching Error*	Err	Output to output variation—all outputs on, $R_{EXT}$ = 5 k $\Omega$	7	-	7	%	
Output Voltage Range	V <sub>DS(min)</sub>		1.0	-	3.0	V	
Load Regulation		I <sub>%Diff</sub> / V <sub>DS</sub>	_	±1	±3	%	
Output Leakage Current	I <sub>DSX</sub>	V <sub>OH</sub> = 17 V	_	_	1.0	μA	
<u> </u>	V <sub>IH</sub>	Off	2.0	_	_	V	
Logic Input Voltage	V <sub>IL</sub>		_	_	0.8	V	
Logic Input Voltage Hysteresis	IL.	All digital inputs	_	150	_	mV	
Logic Input Current	I <sub>IN</sub>	V <sub>IN</sub> = 0 to 5 V	-20	_	20	μA	
<u> </u>	V <sub>OL</sub>	$V_{IN} \ge 5.0 \text{ V, } I_{O} = \pm 2 \text{ mA}$	_	_	0.4	V	
Logic Output Voltage	V <sub>OH</sub>	114 7 0	3.8	_	_	V	
		OEI pin, pull-up	150	300	600	kΩ	
Input Resistance	R <sub>I</sub>	LI pin, pull-down	100	200	400	kΩ	
Output Dot Correction Error		R <sub>EXT</sub> = 5 kΩ; LSB	_	±1	_	bit	
Thermal Shutdown Temperature	T <sub>JTSD</sub>	Temperature increasing	_	165	_	°C	
Thermal Shutdown Hysteresis	T <sub>Jhys</sub>		_	15	_	°C	
SWITCHING CHARACTERISTICS	Julys						
Clock Hold Time	t <sub>H(CLK)</sub>		20	_	_	ns	
Data Setup Time	t <sub>SU(D)</sub>		20	_	_	ns	
Data Hold Time	t <sub>H(D)</sub>		20	_	_	ns	
Latch Setup Time	t <sub>SU(LE)</sub>		20	_	_	ns	
Latch Hold Time	t <sub>H(LE)</sub>		20	_	_	ns	
Output Enable Set Up Time	t <sub>SU(OE)</sub>		40	_	_	ns	
Output Enable Falling to Outputs Turning ON							
Propagation Delay Time	t <sub>P(OE)2</sub>		_	200	_	ns	
Clock to Output Propagation Delay Time	t <sub>P(OUT)</sub>	V <sub>DS</sub> = 1.0 V, I <sub>O</sub> = 150 mA	_	200	_	ns	
Logic Output Fall Time	t <sub>BF</sub>	C <sub>OB</sub> = 50 pF, 4.5 to 0.5 V	_	50	100	ns	
Logic Output Rise Time	t <sub>BR</sub>	C <sub>OB</sub> = 50 pF, 0.5 to 4.5 V	_	30	60	ns	
0.4 45 45 45 000		$C_0 = 10 \text{ pF}, 90\% \text{ to } 10\% \text{ of } I_0 = 10 \text{ mA}$	_	10	_	ns	
Output Fall Time (Turn Off)	t <sub>f</sub>	C <sub>O</sub> = 10 pF, 90% to 10% of I <sub>O</sub> = 10 mA	_	10	_	ns	
0.1 (B) T (T 0.)		C <sub>O</sub> = 10 pF, 90% to 10% of I <sub>O</sub> = 10 mA	_	50	_	ns	
Output Rise Time (Turn On)	t <sub>r</sub>	$C_0$ = 10 pF, 90% to 10% of $I_0$ = 10 mA	_	100	_	ns	
Clock Falling Edge to Serial Data Out Propagation Delay Time	t <sub>P(SDO)</sub>		_	50	100	ns	
Output Enable In to Output Enable Out Propagation Delay	t <sub>P(OE)</sub>		_	50	100	ns	
Latch In to Latch Out Propagation Delay	t <sub>P(LE)</sub>		_	50	100	ns	
Clock In to Clock Out Propagation Delay	t <sub>P(CLK)</sub>		_	50	100	ns	
Clock Out Pulse Duration	t <sub>w(CLK)</sub>		70	100	130	ns	
Maximum CLKIN Frequency	f <sub>CLKIN</sub>		-	-	6	MHz	
maximam Service requestoy	CLKIN					171112	

<sup>\*</sup>Err =  $[I_O(min \text{ or } max) - I_O(av)] / I_O(av)$ .



# **Timing Diagram**

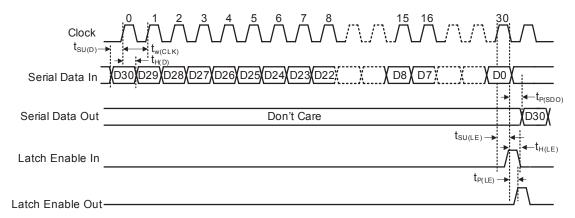


Figure 2. Shift Register Timing

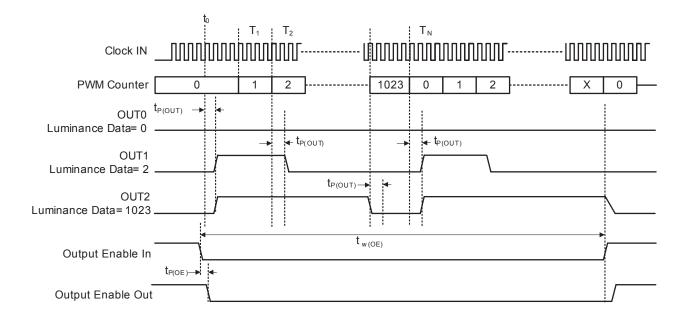


Figure 3. PWM Counter and Output Timing



# **Functional Description**

#### **Shift Registers**

The A6280 has a 31 bit shift register that loads data through the Serial Data In (SDI) pin. The shift registers operate by a first-in first-out (FIFO) method. The most significant bit (MSB, bit 30) is the first bit shifted in and the least significant bit (LSB, bit 0) is shifted in last. The serial data is clocked by a rising edge of the Clock In (CI) pin. The Serial Data Out (SDO) pin is updated to the state of bit 30 on the falling edge of the CI pin. This will prevent any race conditions and erroneous data that might occur while propagating information through multiple A6280 that are daisy chained together. The contents of the shift registers will continue to propagate on every rising edge of the CI pin. The information in the shift registers is latched on a rising edge of the Latch In (LI) pin. The latched data remains latched on a rising Output Enable In (OEI) signal.

# **Output Buffers**

The A6280 is designed to allow daisy chaining many A6280s together. It has the ability to pass the clock, data, latch, and output enable signals from one A6820 to the next without any loss of data due to duty cycle skewing or signal degradation.

The A6820 is equipped with output buffers that allow the data signals to travel over long distances through strings of A6280s without the need for extra driving hardware. The A6280 drives these signals to TTL levels. Each of the A6280 inputs have a corresponding buffered output:

- Clock In (CI) pin to Clock Out (CO) pin
- Latch In (LI) pin to Latch Out (LO) pin
- Output Enable In (OEI) pin to Output Enable Out (OEO) pin
- Serial Data In (SDI) pin to Serial Data Out (SDO) pin

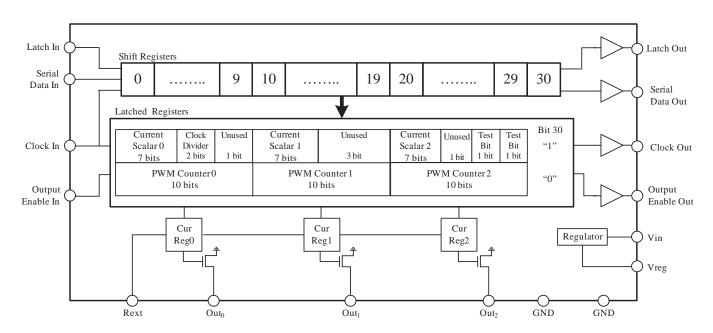


Figure 4. Functional Diagram



#### **PWM Luminance Control**

The A6280 controls the intensity of each LED by PWMing the current of each output. The A6280 has three 10 bit luminance registers, one for each output. These luminance registers set the PWM count value at which the outputs switch off during each PWM cycle. Each 10 bit luminance register gives 1023 levels of light intensity. The duty cycle, DC (%), can be determined by the following equation:

$$DC = [(PWM_{n+1})/1024] \times 100$$
,

where  $PWM_n$  is the PWM value greater than zero that is stored in the luminance register. When the luminance register is set to zero, the outputs remain off for the duration of the PWM cycle for a 0% DC. When a luminance register is set to 1023, the LED for that output remains on (100% DC) when OEI is active and begins the PWM cycle. The output remains on when the PWM counter rolls over and begins a new count.

The PWM counter begins counting at zero and increments only when the OEI pin is held low. When the PWM counter reaches the count of 1023, the counter resets to zero and continues incrementing. The counter resets back to zero either on a rising edge of OEI, upon recovery from UVLO, or when powering up. Latching new data into the luminance registers will not reset the PWM counter.

There is a programmable clock divider that attenuates the clock input of the CI pin. See table 1 for bit assignments of the programmable clock divider. The PWM counter is incremented on every rising edge of the CI pin divided by the clock divider count value when the OEI pin is low. For example, if the clock divider is programmed to divide the CI by 2, then the PWM counter will increment once every 2 CI cycles. Given a 5 MHz CI frequency, the clock period would be 200 ns.

**Table 1. Clock Divider Configurations** 

В	its	Divide By Count	
7	8	Divide by Count	
0	0	×1 (no division)	
1	0	×2	
0	1	×4	
1	1	×8	

The clock divider data in the shift registers is latched on a rising edge of the Latch In (LI) pin. The latched clock divider data remains latched on a rising OEI signal.

The total number of possible colors of an RGB pixel is over 1 billion. Refer to figure 6 for the mapping of shift register bits to latches.

## **Output Current Selection**

The overall maximum current is set by the external resistor,  $R_{\rm EXT}$ , connected between REXT and LGND. Once set, the maximum current remains constant regardless of the LED voltage variation, supply voltage variation, temperature, or other circuit parameters that could otherwise affect LED current. The maximum output current can be calculated using the following equation:

$$I_{O}(max) = 753.12 / R_{EXT}$$

The relationship of the value selected for  $R_{EXT}$  and  $I_{O}$  is shown in figure 5.

## **Internal Linear Regulator**

The A6280 has a built-in linear regulator. The regulator operates from 5 to 17 V, and is intended to allow the VIN pin of the A6280 to connect to the same supply as the LEDs. This will simplify board design by eliminating the need for a chip supply bus and external voltage regulators.

The VREG pin is used by the internal liner regulator as an energy reservoir. This pin is for internal use only and is not intended as an external power source. The VREG pin should have a 1.0  $\mu$ F, 10 V ceramic capacitor connected between the VREG pin and LGND. The capacitor should be located as close to the VREG pin as possible.

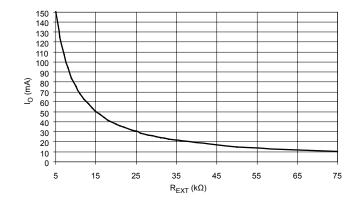


Figure 5. Output Current versus External Resistor,  $R_{\text{EXT}}$ 



#### **Dot Correction Control**

The A6280 can further control the maximum output current for each output by setting the three 7 bit dot correction registers with scale data that ranges from 36.5% to 100% of the overall maximum output current that is set by the  $R_{\rm EXT}$  resistor. This feature is useful because not every type of LED (red, green, or blue, for example) has the same level of brightness or intensity for any given current, and the brightness could be different even from LED to LED of the same type. By scaling the output currents so that all the LEDs have matched intensities, the application will have full color depth when using the PWM counters. The dot correction current can be calculated by the following equation:

$$I_{On} = I_{On(max)} \times (Scale_n / 2 + 36.5)$$

Refer to figure 6 for the bit configurations for the scalar registers.

The dot correction data in the shift registers is latched on a rising edge of the Latch In (LI) pin. The latched dot correction data remains latched on a rising OEI signal. The default output current when the A6280 is powered up or recovers from a UVLO is 36.5% of the current set by the  $R_{\rm EXT}$  resistor.

# **Package Power Dissipation**

The maximum allowable package power dissipation is determined as:

$$P_D(max) = (150 - T_A)/R_{\theta JA}$$
.

The actual package power dissipation is:

$$\begin{split} P_{D(act)} &= DC_0 \times V_{DS0} \times I_{OUT0} \\ &+ DC_1 \times V_{DS1} \times I_{OUT1} \\ &+ DC_2 \times V_{DS2} \times I_{OUT2} + V_{IN} \times I_{IN} \enspace . \end{split}$$

When calculating power dissipation, the total number of available device outputs is usually used for the worst-case situation (i.e., displaying all 3 LEDs at 100% DC).

#### Thermal Shutdown (TSD)

When the junction temperature of the A6280 reaches the thermal shutdown temperature threshold,  $T_{JTSD}$  (165°C typical), the outputs will shut off until the junction temperature cools down below the recovery threshold,  $-T_{JTSD} - \Delta T_J$  (15°C typical). The shift registers and output latches will remain active during the TSD event. Therefore there is no need to reset the data in the output latches.

#### **Undervoltage Lockout**

The A6280 includes an internal undervoltage lockout (UVLO) circuit that disables the driver outputs in the event of the logic supply voltage dropping below a minimum acceptable level. This prevents the display of erroneous information, a necessary function for some critical applications. The shift registers will not shift any data in a UVLO condition. Upon recovery of the logic supply voltage and on power up, all internal shift registers and latches will be set to zero.

#### **Ballast Resistors**

The voltage on the outputs should be kept in the range 1 to 3 V. If the voltage goes below 1V, the current will begin to rolloff as the driver runs out of headroom. At  $V_O$  above 3 V, the power dissipation may become a problem, as each output contributes  $V_O \times I_{LED}$  of power loss in the output sink driver. Typically the power supply nominal voltage is chosen to keep the output voltage in this range. Alternatively, series resistors can be added to dissipate the extra power and keep the output voltage within the recommended range.

	:4.
н	IT S

C	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30
			PW	M (	Cou	nte	r 0				PWM Counter 1							PWM Counter 2									0			
	Dot Correction Clock Register 0 Divider				0			ot C Reg			on		0	0	0					ecti er 2			0	ATB*	ATB*	1				

<sup>\*</sup>Allegro Test Bit (ATB). Reserved for Allegro internal testing. Always set to zero (0) in the application.

Figure 6. Register Configuration



# **Applications Drawings**

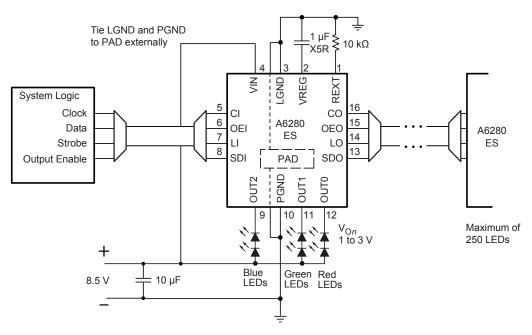


Figure 7. Application Driving 3 RGB LEDs at 75 mA Peak

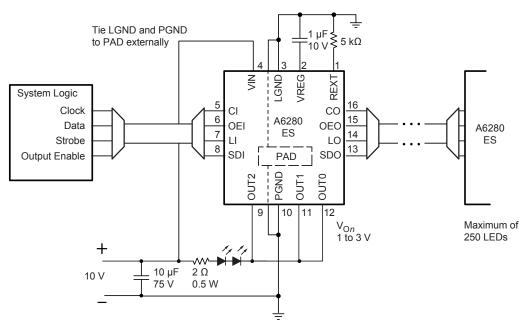


Figure 8. Application Driving High Power LED at 450 mA



# A Package, 16 Pin DIP

Preliminary dimensions, for reference only Dimensions in inches

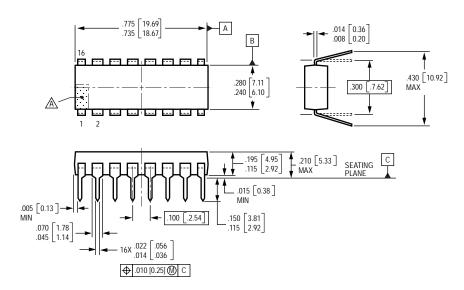
Metric dimensions (mm) in brackets, for reference only

(reference JEDEC MS-001 BB)

Dimensions exclusive of mold flash, gate burrs, and dambar protrusions

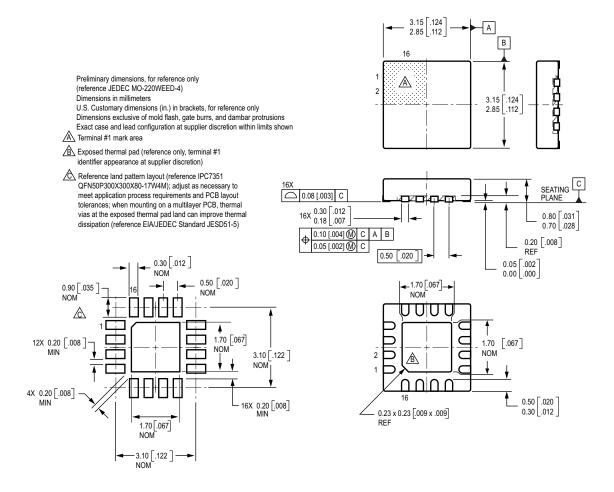
Exact case and lead configuration at supplier discretion within limits shown

Terminal #1 mark area





## ES Package, 16 Pin QFN/MLP



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